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**Second Semester M.Tech. Degree Examination, June/July 2016**  
**Computer Control of Manufacturing Systems**

Time: 3 hrs.

Max. Marks: 100

**Note: 1. Answer any FIVE full questions.**  
**2. Assume missing data suitably.**

- 1 a. Explain with neat sketch the product cycle with CAD/CAM overlaid. (10 Marks)  
b. What is CIMS? Explain the functions of computer in CIMS. (10 Marks)
- 2 a. Explain with a neat sketch the different components of a hydraulic system. (10 Marks)  
b. Briefly explain the incremental and absolute encoders used for rotary position measurement with neat sketches. (10 Marks)
- 3 a. With help of a block diagram explain the working of incremental closed loop control of a point to point system. (10 Marks)  
b. Explain the principle of operation of a control loop in the contouring system. (10 Marks)
- 4 a. Explain the neat sketches the tool changing procedure in an ATC (Automatic Tool Change) having durable gripper. (12 Marks)  
b. With neat sketch describe any two work holding devices used in CNC machine tools. (08 Marks)
- 5 a. Write the functions associated with the following G and M codes cost FANUC controllers.  
i) G03 ii) G04 iii) G41 iv) G80 v) G91 vi) M02 vii) M06 viii) M98 (08 Marks)  
b. Examine the following CNC part program for a machining centre equipped with a FANUC controller. Identify any errors found in the program and explain the errors.  
Prepare the geometry of the part generated if the diameter of the slot drill used is 10mm.  
[BILLET O 7001 X Y Z  
N1 G71  
N2 G90  
N3 T1 M6  
N4 G0 X75 Y 100  
N5 G1 Z - 3  
N6 X175 F100  
N7 Y25  
N8 X75  
N9 Y100  
N10 M30. (12 Marks)
- 6 a. Explain the functions of a Computer Numerical Control (CNC). (10 Marks)  
b. What is DNC? With a neat sketch explain a general DNC system. (05 Marks)  
c. Explain in brief the sources of variability in machining where adaptive control can be most suitably applied. (05 Marks)
- 7 a. With a neat sketch list the physical 6 DOF in robot motion. (08 Marks)  
b. Explain in brief the sensors used in Robots. (06 Marks)  
c. Briefly explain the 4 methods used for programming a robot. (06 Marks)
- 8 a. Explain with a block diagram the variant CAPP system. (10 Marks)  
b. List and explain the steps involved in shop floor control system. (10Marks)

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